# Novel Robotic Techniques for Endoscopic Resection of Large Polyps

Joe Carmichael, MD | February 2, 2018 10<sup>th</sup> Annual Gastroenterology & Hepatology Symposium



#### **Disclosures**

Medrobotics



#### Large Polyps

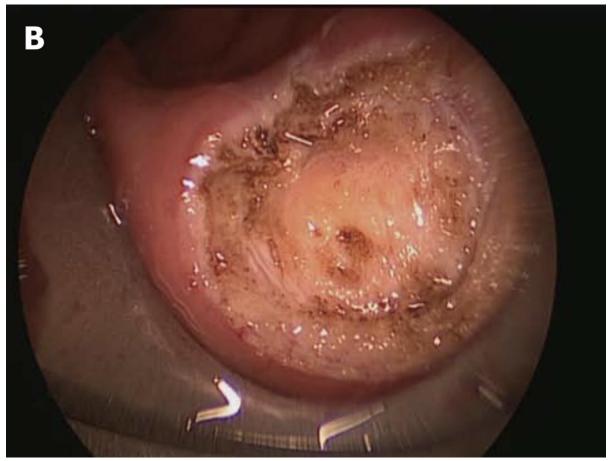
- Some large rectal polyps (and many early rectal cancers) cannot be removed endoscopically
- These patients are frequently referred for surgical excision
- Surgical options have traditionally included:
  - Transanal excision (TAE)
  - Transanal endoscopic microsurgery (TEM)
  - Transanal Minimally Invasive Surgery (TAMIS)





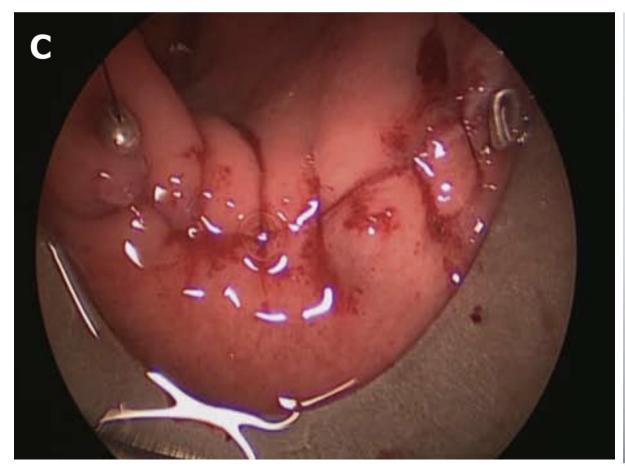
#### **TEM of Neuroendocrine Tumor**

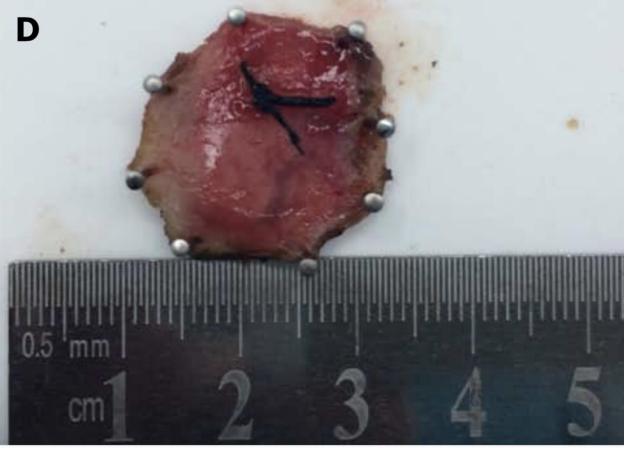






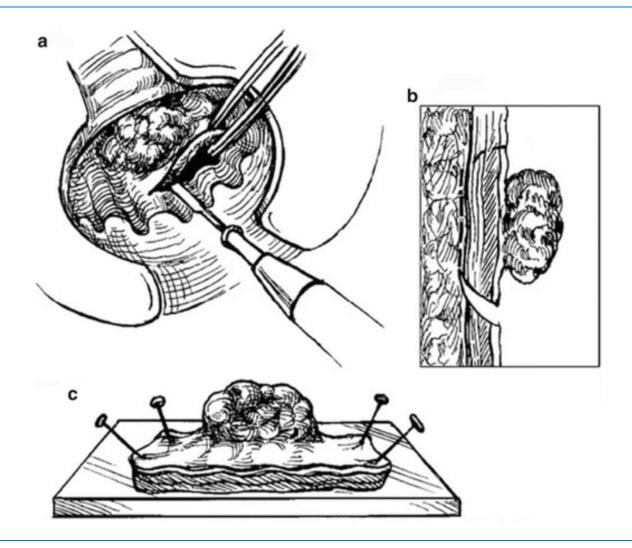
#### **TEM of Neuroendocrine Tumor**







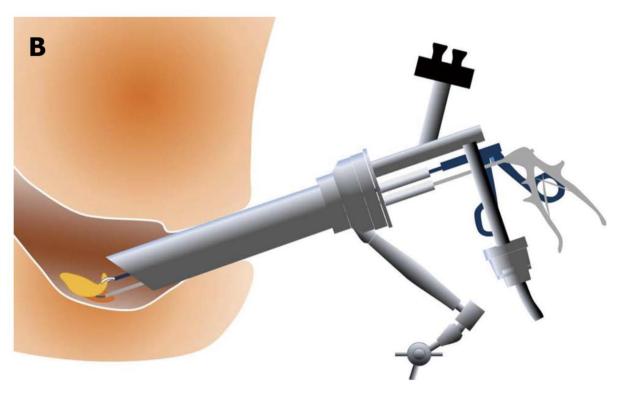
#### **Traditional Transanal Excision**





#### Transanal Endoscopic Microsurgery (TEM)



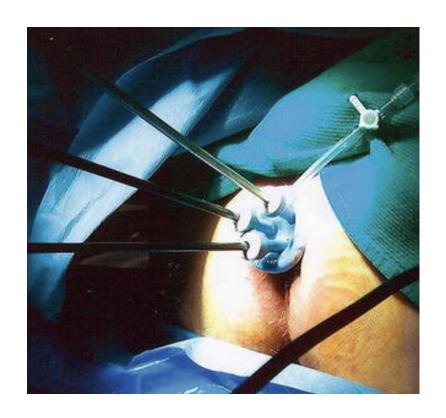






### Transanal Minimally Invasive Surgery (TAMIS)





### Transanal Minimally Invasive Surgery (TAMIS)







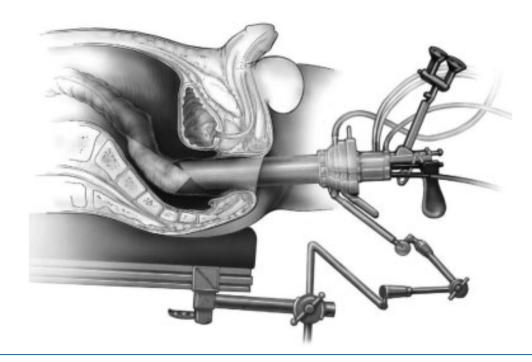
#### TEM/TAMIS Advantages over Transanal Excision

#### Transanal excision:

- Limited to polyps tumors 6-8cm from the anal verge
- Limited to smaller polyps/tumors
- Associated with higher recurrence rates of polyps and tumors compared with TEM/TAMIS

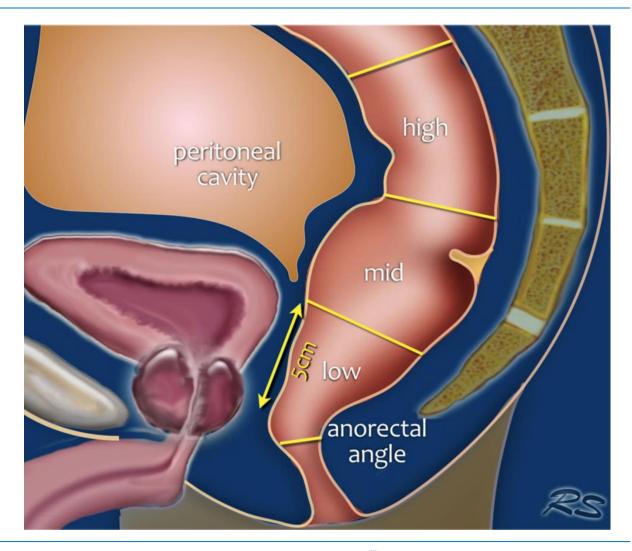
#### • TEM/TAMIS:

- Allows for excision of mid/high rectal tumors
- Allows for excision of large tumors
- Allows for full thickness excision
- Limited by need for straight anoscope





- Low Rectum → Transanal Excision
- Mid Rectum → TEM/TAMIS
- High Rectum → ??





- Operator-controlled, computerassisted flexible endoscope
- Enables the physician to easily access and visualize anatomical structure through a transoral approach
- Provides 2 accessory channels for compatible flexible instruments





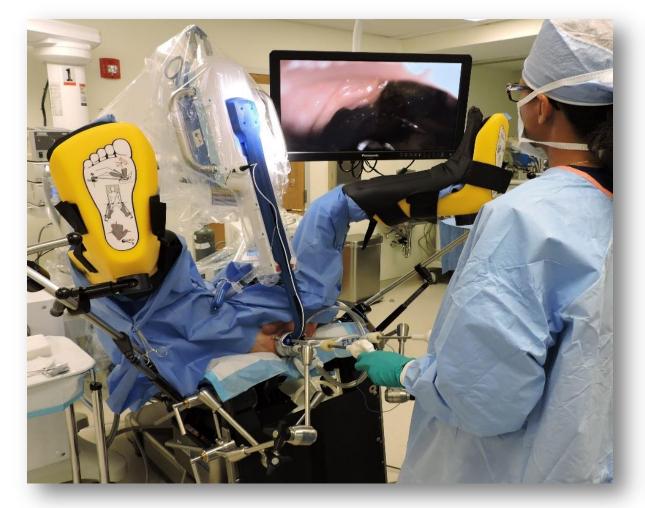






- This system was originally applied to oral surgery
- Feasibility was originally demonstrated in removing lesions in the oropharynx, hypopharynx and larynx

## Why can't flexible robotics be an alternative tor TEM and TAMIS to reach high rectal/sigmoid lesions?







#### Technical Challenges for Transanal Access

- Need to seal the links of the robot to maintain pneumorectum
- Develop compatible access device
- Refine instrumentation
- Cadaveric and procine testing to demonstrate feasibility for transanal surgery



#### **Cadaveric Assessment**

Objectives/ Hypothesis	To evaluate the Medrobotics Flex® Robotic System and Flex® Rectoscope's ability to facilitate access for and visualization of surgical resection and closure within the rectum using Flex® Instruments via a transanal entry	
Study Design	Preclinical anatomic study utilizing 6 cadavers	
Methods	2 surgeons participated in this study Each participant utilized the Flex® Robotic System to excise and close rectal wall specimens.	
Results	14/14 (100%) resected successfully 13/14 (93%) closed successfully	
Conclusion	This study provides evidence that the Flex® Robotic System, Flex® Rectoscope, and Flex® Instruments can be used to perform transanal colorectal surgical procedures (tissue resection and resection closure) with a high degree of success.	



#### Porcine Assessment

- The porcine study was designed to evaluate Flex® Robotic System's wound closure vs a TEM system (Storz® TEO) in a live tissue model
- Eight swine
  - 2 control animals
  - 6 test animals
  - Rectal wall excision and closure
- Grade excision site 7 days after closure



Porcine Wound Scoring & Characteristics			
0	No separation of wound edges/No edema/No inflammation		
1	Mild (< 2 mm) separation of wound edges; mild tissue edema, bleeding surfaces or inflammation		
2	Moderate separation of wound edges (>2 mm but < 1 cm): moderate surrounding tissue edema, moderate oozing surfaces, or inflammation		
3	Complete separation of wound edges (>1 cm): severe tissue edema, extensive oozing surfaces, or inflammation		

	Storz® TEO	Flex® Robotic System
N	2	6
Mean Surgical Site	0	0.3
StDevP Surgical Site	0	0.5
Mean Surgical Area	0	0
StDevP Surgical Area	0	0



### **Excision of Rectosigmoid Junction Polyp**



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